

# SIGGRAPH

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# Homomorphic Factorization of BRDFs for High-Performance Rendering

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# Outline

- Introduction
- Previous Work
- Factorization
- Results
- Conclusions

# Introduction

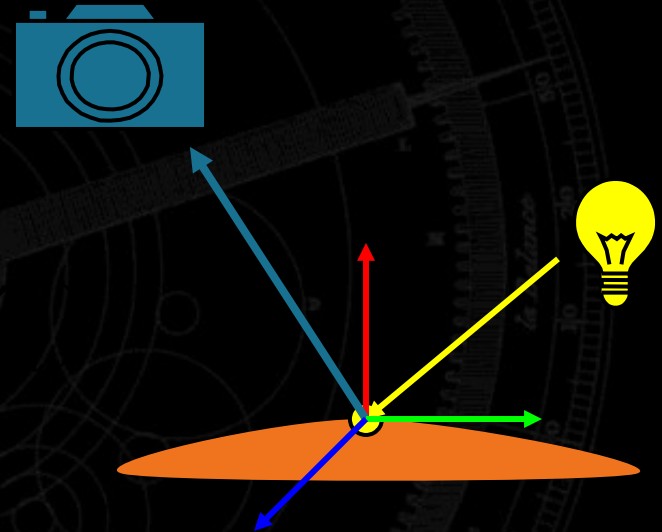
- What is a bidirectional reflectance distribution function (BRDF)?
- Why use BRDFs?

# Introduction

- **BRDF properties:**
  - Helmholtz reciprocity
  - Conservation of energy
- **BRDF classes:**
  - Isotropic
  - Anisotropic

# BRDF

- Functional notation:
- Assume shift-invariant:
- Omit wavelength dependence:



# Local Lighting Equation

- Outgoing radiance from point  $p$  in direction  $\omega_o$  :
- Illumination from  $N$  point sources:

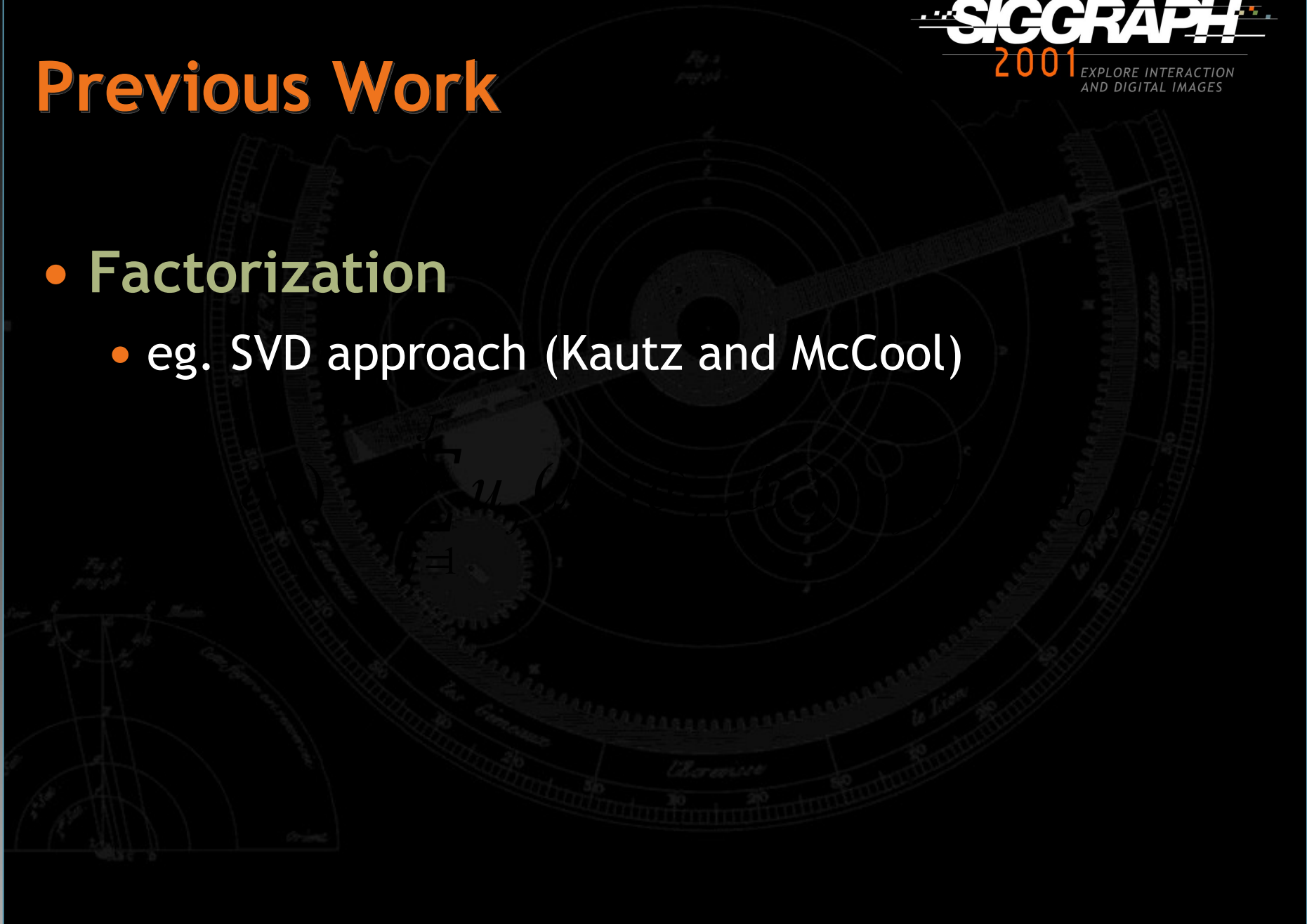
# Previous Work

- **Basis summation**
  - Ward, Lafortune, Foo, Torrance, Greenberg
- **Environment mapping**
  - Kautz, McCool, Vazquez, Heidrich, Seidel
- **Factorization**
  - Kautz, McCool, Vazquez, Heidrich, Fournier



# Previous Work

- Factorization
  - eg. SVD approach (Kautz and McCool)



# Factorization

- Approximate  $f$  using product of positive factors:
- Take logarithm of both sides:

# Factorization

- Notice this is just a linear data-fitting problem:



# Parameterization

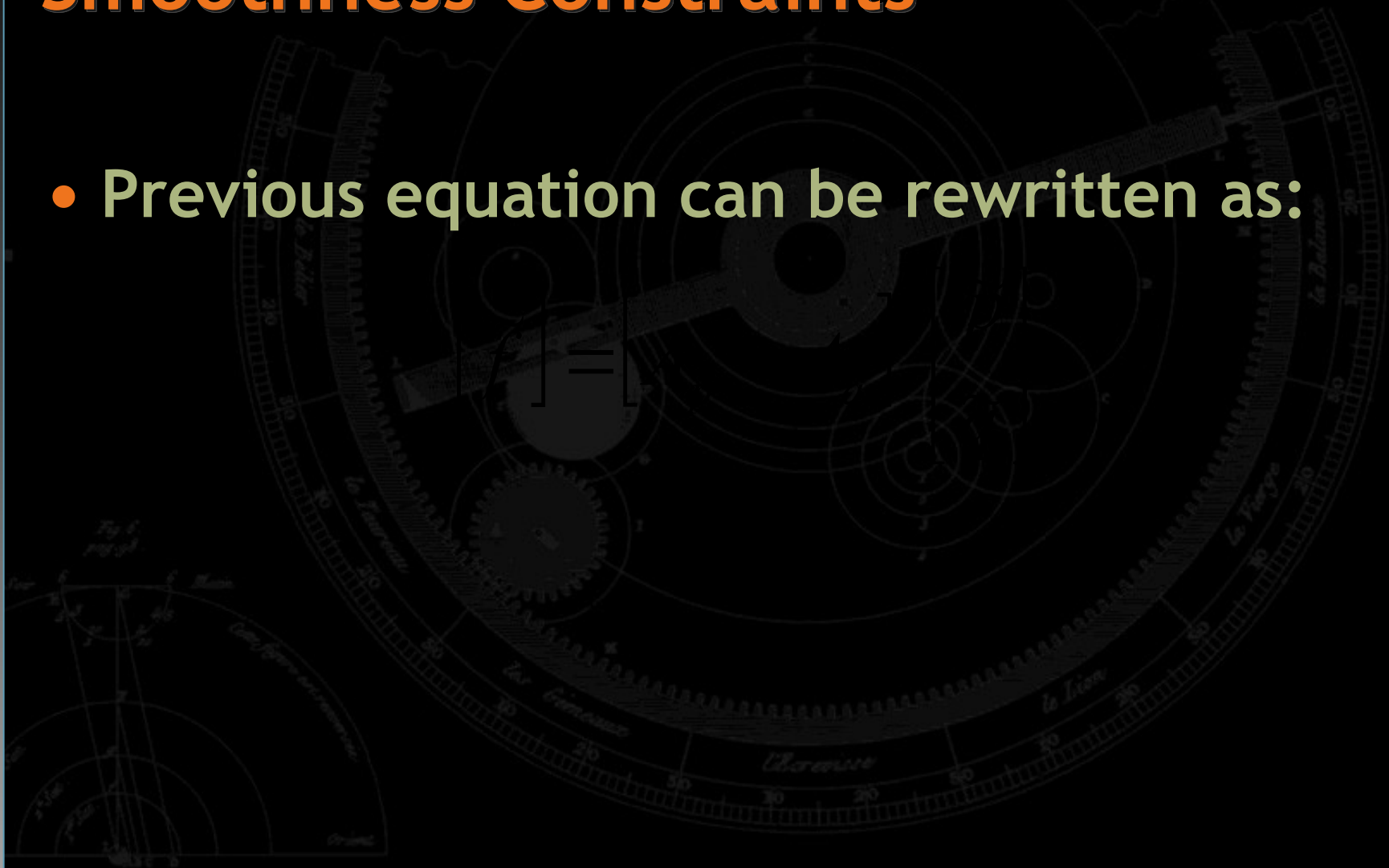
- Choose parameterization:
  - Easy to compute parameters
  - Three factors stored in two texture maps
- Take logarithm:

# Data Constraints

- Need to find  $p$  and  $q$ :
  - Set up linear constraints relating samples in  $f$  to texels in  $p$  and  $q$
  - Use bilinear weighting factors

# Smoothness Constraints

- Previous equation can be rewritten as:



# Smoothness Constraints

- Add constraints to equate Laplacian with zero:

- Ensures every texel has a constraint

$\forall \lambda$  controls the smoothness of solution

# Iterative Solution

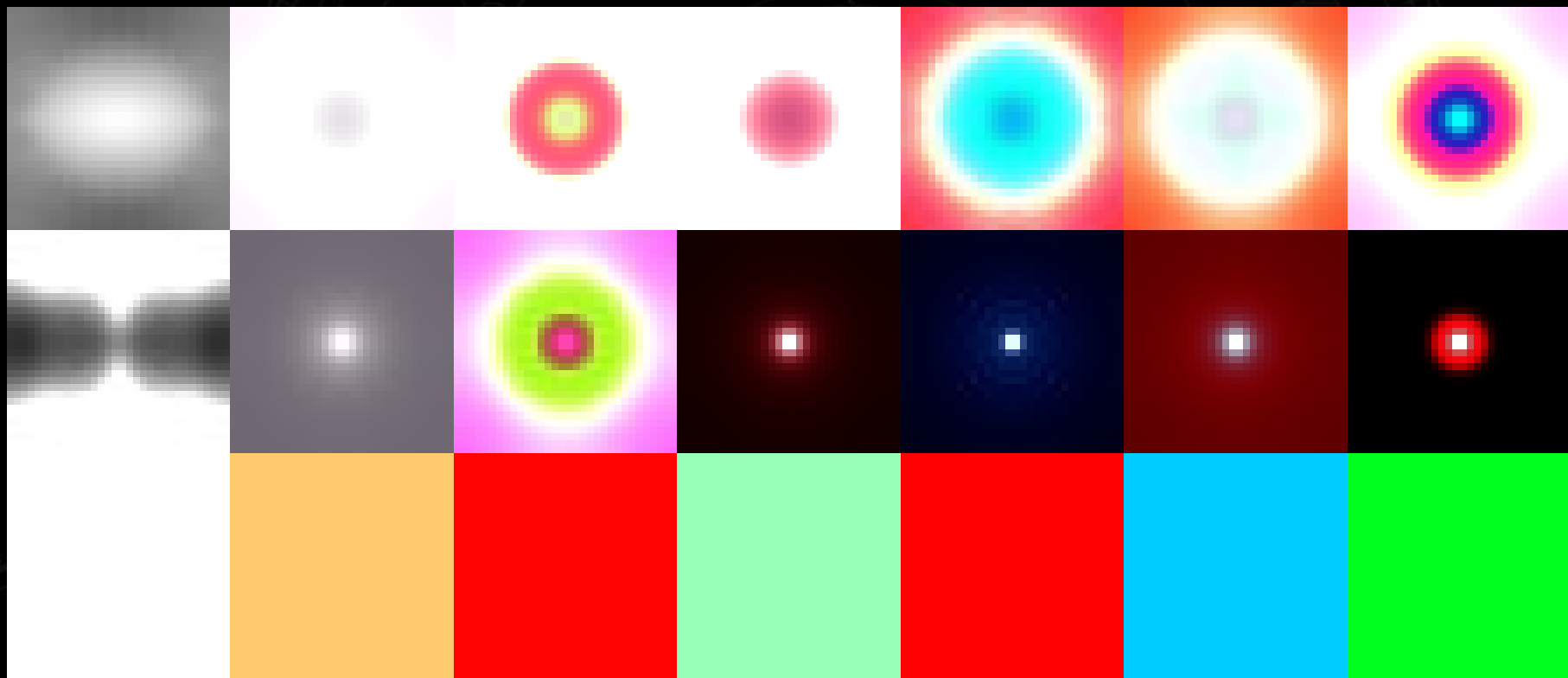
- Solve using quasi-minimal residual (QMR) algorithm in IML++
  - Freund and Nachtigal (1991)
  - Estimate an initial solution by averaging
  - Apply at multiple resolutions
- Divide  $p$  and  $q$  by their maximums and combine scale factors into a single colour  $\alpha$



# Rendering

- Reconstruction equation:
  - $N$  passes on the NVIDIA GeForce 3 using
    - OpenGL 1.2
    - Multitexturing extensions
    - Register combiner extensions
    - Vertex program extensions
    - Compositing

# Results

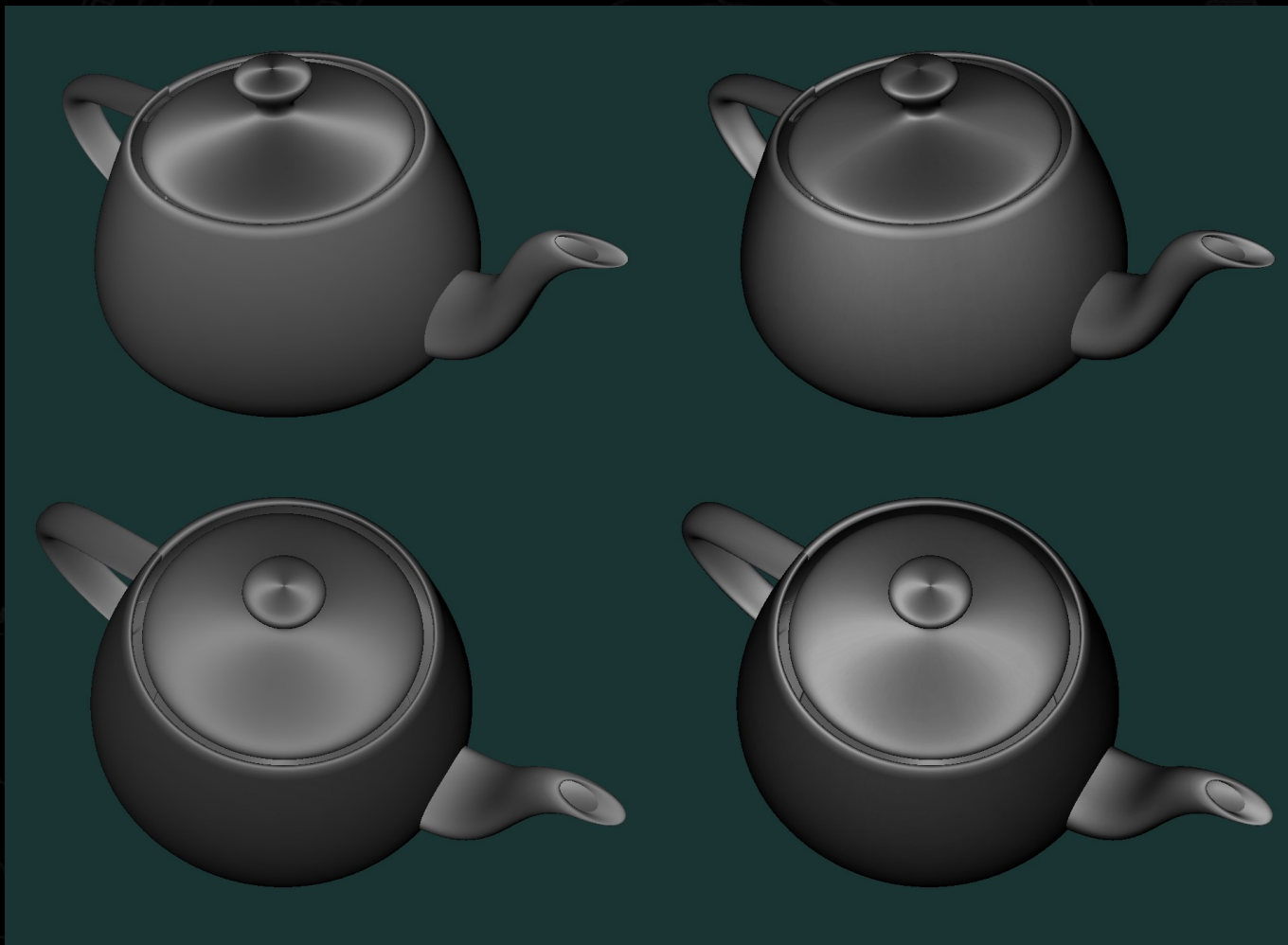


- Top to bottom:  $p'$ ,  $q'$  texture maps (32 x 32) and  $\alpha$ .
- Left to right: satin (Poulin-Fournier analytic), leather, velvet (CURET), garnet red, krylon blue, cayman, mystique (Cornell).

# Results

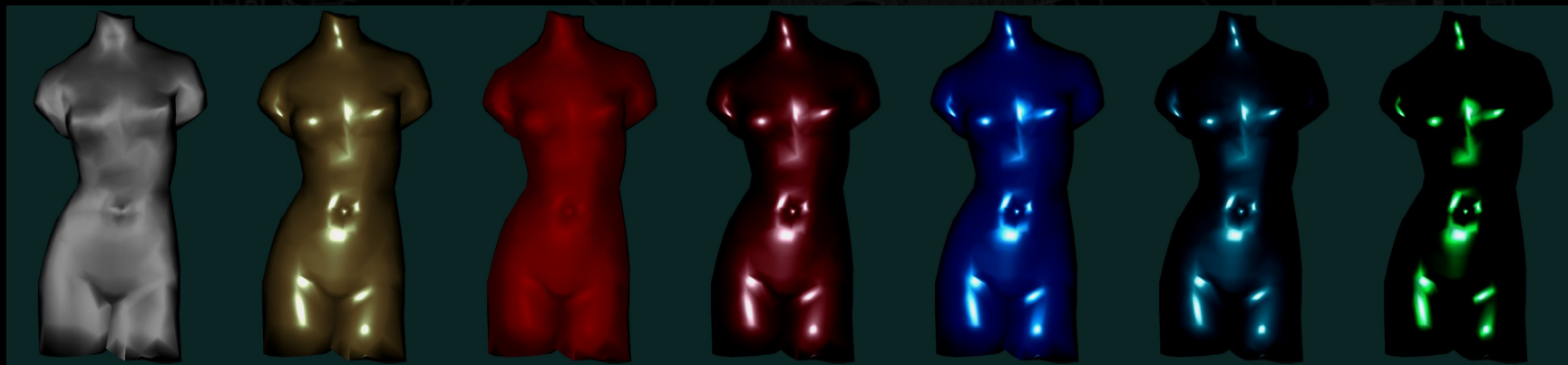
- Venus de Milo model with 90752 triangles
- Pentium 4 1.4 GHz, 640 MB, NVIDIA GeForce 3 AGP 4x @ 1280x1024x32bit
- Standard OpenGL Lambertian lighting:
  - 123 fps, 11.2 Mtri/s
- Full illumination:
  - 76 fps, 6.9 Mtri/s

# Approximation Error



# Live Demo

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# Conclusions

- **New BRDF factorization algorithm**
  - Achieves reasonable compression ratios
  - Minimizes relative error in approximation
  - Flexible choice of parameterization
  - Results are positive factors
  - Can handle sparse data, reuse texture maps
  - Renders in real-time rates in current hardware

# Acknowledgements

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- NSERC, CITO